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Proceedings of the 2002 IEEEInternational Conference on Robotics AutomationWashington DC May 2002Safety-optimizing Method of Hmrmn-care Robot Design and ControlMakoto NOKATA Koji IKUTA Hideki ISHIIDepartment of Micro System Engineering School of Engineering Nagoya UniversityFuro-cho Chikusa-ku Nagoya-shi Aichi 464-8603 JAPANAbstract First we select a suitable physical parameter as an eval-We propo...

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Philip D. Reiner, Arthur J. Duncan III, Russell Durham
 Abstract: This paper discusses a remote control 2. Speech Recognition system for a mobile robot using voice commands sent wirelessly over a network to a mobile robot. In order to realize a voice controlled robot, there must be some way to recognize the commands 1. Introduction coming from a voice. Robust software libraries have already been deve...

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Laurel D Riek¹ and Peter Robinson
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 Maze exploration behaviors using an integrated evolutionary robotics environment
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